

# A conjecture concerning a limit of non-Cayley graphs

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## Abstract

Our aim in this note is to present a transitive graph that we conjecture is not quasi-isometric to any Cayley graph. No such graph is currently known. Our graph arises both as an abstract limit in a suitable space of graphs and in a concrete way as a subset of a product of trees.

## 1. Introduction

Woess [7] asked the following beautiful and natural question: does every transitive graph ‘look like’ a Cayley graph? More precisely, is every connected locally finite vertex-transitive graph quasi-isometric to some Cayley graph?

Let us recall that graphs  $G$  and  $H$  are said to be *quasi-isometric* if there exist Lipschitz mappings  $\theta: V(G) \rightarrow V(H)$  and  $\phi: V(H) \rightarrow V(G)$  such that  $\theta \circ \phi$  and  $\phi \circ \theta$  are bounded. Equivalently,  $G$  and  $H$  are quasi-isometric if there exists a *quasi-isometry* from  $G$  to  $H$ , a function  $\theta: V(G) \rightarrow V(H)$  for which there are constants  $C, D \geq 1$  such that

$$d(\theta x, \theta y) \leq Cd(x, y) \text{ for all } x, y \in G,$$

$$d(\theta x, \theta y) \geq \frac{1}{C}d(x, y) \text{ for all } x, y \in G \text{ with } d(x, y) \geq D,$$

$$d(\theta G, y) \leq D \text{ for all } y \in H,$$

where as usual  $d$  denotes the graph distance (in  $G$  or  $H$ ) and  $d(A, y) = \min \{d(x, y) : x \in A\}$ .

Thus quasi-isometry is the natural notion of ‘looks the same as, from far away’. Many properties of a graph are preserved under quasi-isometry – for example, the space of ends is preserved. As another example, if  $G$  and  $H$  are transitive graphs that are quasi-isometric then they have the same type of growth: polynomial or sub-exponential or exponential. See [2] for background on quasi-isometry.

Let us also recall that a *Cayley graph* is a graph arising in the following way. Let  $G$  be a group, with a finite generating set  $S$  closed under inversion

(ie.  $a \in S$  implies  $a^{-1} \in S$ ). Then the (left) Cayley graph of  $G$  with respect to  $S$  has vertex-set  $G$ , with  $x$  joined to  $y$  if for some  $a \in S$  we have  $x = ay$ . Note that  $G$  acts freely (ie. with no non-identity element having a fixed point) and transitively on this graph. In fact, Cayley graphs are characterised by this property: if  $G$  is any locally finite connected graph whose automorphism group  $\text{Aut } G$  has a subgroup that acts transitively and freely on  $G$  then  $G$  is easily seen to be isomorphic to a Cayley graph of that subgroup. See [3] for more background on Cayley graphs. Let us also mention here that, up to quasi-isometry, the Cayley graph of a (finitely-generated) group does not depend on which generating set one chooses.

Several transitive graphs are known that are not (isomorphic to) Cayley graphs (see [4],[5]), but each of these is quasi-isometric to a Cayley graph. Indeed, the answer to Woess' question is known to be in the affirmative for several classes of graphs, including those of polynomial growth [6].

Our aim in this note is to present a graph that we believe is a counterexample to Woess' question. We construct a sequence of graphs that seem to look less and less like Cayley graphs. It turns out that this sequence has a limit when viewed in a certain natural space of graphs. We give this construction in Section 2.

Fortunately, this limit graph can also be expressed 'concretely', as a certain subset of a product of two trees. We do this in Section 3. We hope that this should make the conjecture that this graph is not quasi-isometric to a Cayley graph more susceptible to proof.

## 2. A limit of non-Cayley graphs

Our starting point is the following example of Thomassen and Watkins [5] of a non-Cayley graph. Let  $H$  be the graph obtained from a  $T_5$  (the infinite 5-regular tree) by replacing each vertex by a  $K_{2,3}$  (the complete bipartite graph with vertex classes of size 2 and 3) in the following way. Replace each vertex of  $T_5$  by a disjoint copy of  $K_{2,3}$ , and then, for each edge  $uv$  of the  $T_5$ , identify a vertex of the  $K_{2,3}$  corresponding to  $u$  with a vertex of the  $K_{2,3}$  corresponding to  $v$ , in such a way that no point in any  $K_{2,3}$  is identified more than once, and a vertex in a class of size 2 is always identified with a vertex in a class of size 3 and vice versa (see Figure 1). Then  $H$  is certainly transitive (of degree 5); why is it not a Cayley graph?

Suppose there is a subgroup  $S$  of  $\text{Aut } H$  that acts freely and transitively on  $H$ , and let  $K$  be one of the  $K_{2,3}$ s making up  $H$  – say  $K$  has vertex classes  $\{x_1, x_2\}$  and  $\{y_1, y_2, y_3\}$ . Any automorphism that sends an element of  $\{y_1, y_2, y_3\}$  back into  $\{y_1, y_2, y_3\}$  must fix  $K$  – indeed, it must map the set  $\{x_1, x_2\}$  to itself, as  $\{x_1, x_2\}$  is the only pair of two vertices that has 3 common neighbours and has a common neighbour in the set  $\{y_1, y_2, y_3\}$ . Hence the  $\theta \in S$

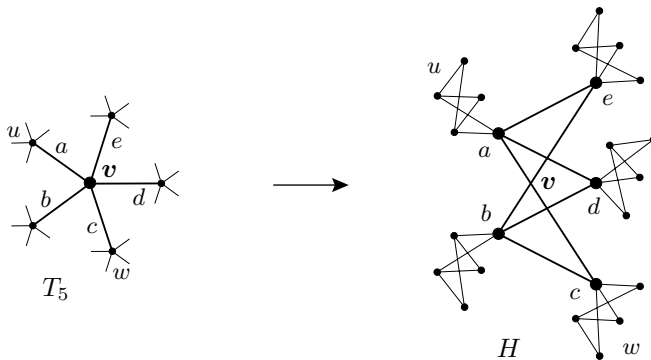


FIGURE 1. Constructing the non-Cayley graph  $H$  from  $T_5$

sending  $y_1$  to  $y_2$  must swap  $x_1$  and  $x_2$ , as must the  $\theta' \in S$  sending  $y_1$  to  $y_3$ . But then  $\theta'\theta^{-1}$  sends  $y_2$  to  $y_3$  and fixes  $x_1$ , a contradiction.

Of course,  $H$  is still quasi-isometric to  $T_5$  (which is the Cayley graph of the free group with 5 generators, each of order 2): we just have to map each  $K_{2,3}$  back to the vertex of  $T_5$  from which it was expanded. Thus the  $K_{2,3}$ s are too local to affect quasi-isometry: we would like to introduce something like ‘larger  $K_{2,3}$ s’ to have the same effect more globally. The following idea shows that these can indeed be obtained.

Roughly speaking, the reason why  $H$  is not Cayley is that the insertion of  $K_{2,3}$ s has introduced an ‘orientation’ which all automorphisms must preserve (but cannot all preserve without a fixed point). Indeed, each  $K_{2,3}$  has a natural orientation of its edges from the 2-set to the 3-set, and put together they make  $H$  into a regular directed graph of in-degree 2 and out-degree 3. Our key observation now is that we can reverse this process of obtaining an orientation from  $K_{2,3}$ s to one of obtaining  $K_{2,3}$ s from an orientation. Indeed, if we *start from* a suitable orientation  $D_0$  of  $T_5$ , namely, the regular orientation of in-degree 2 and out-degree 3, then our directed version of  $H$  (with all its useful ‘Cayley-inhibiting’  $K_{2,3}$ s) is obtained from  $D_0$  by one simple operation, which moreover can be iterated canonically to yield ‘larger and larger  $K_{2,3}$ s’ (see Figures 2 and 5): the operation of taking a directed line graph.

Let us do this in more detail. Given a directed graph  $D$ , the *line graph* of  $D$  is the directed graph  $D'$  whose vertices are the arcs  $uv$  of  $D$ , and in which such a vertex  $uv \in V(D')$  sends an arc (of  $D'$ ) to another vertex  $v'w' \in V(D')$  if and only if  $v = v'$ . Note that if  $D$  is regular with in-degree  $a$  and out-degree  $b$  then so is  $D'$ . The operation of taking a line graph can thus be iterated on regular directed graphs without increasing their degrees – a fact that will be vital to our whole approach.

A moment’s thought shows that our directed version of  $H$  is indeed the line graph of  $D_0$ . So for  $i = 1, 2, \dots$  let  $D_i$  be the (directed) line graph of  $D_{i-1}$ , and let  $G_i$  denote the undirected graph underlying  $D_i$ . (Thus,  $G_1 = H$ .) Since

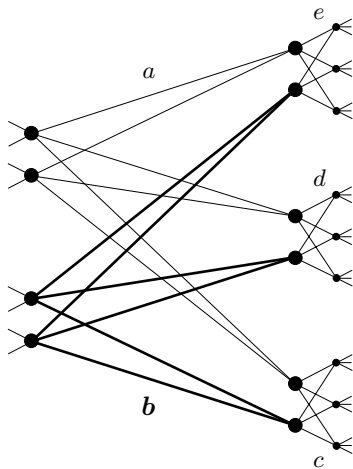


FIGURE 2. The portion of  $G_2$  corresponding to the central  $K_{2,3}$  in Figure 1

every  $D_i$  is regular with in-degree 2 and out-degree 3, all the  $G_i$  are 5-regular; it is therefore not unreasonable to expect that they converge to a graph ‘at infinity’ in some natural sense, and that this limit graph might not be quasi-isometric to a Cayley graph.

In order to define this limit graph precisely, let us pause to explain the (very simple) space of graphs we are working with. For a fixed positive integer  $r$  (which for us will always be 5), let  $Q = Q_r$  denote the set of (isomorphism classes of) all connected  $r$ -regular transitive graphs. We introduce a metric on  $Q$  by setting  $d(G, H) = 1/(n + 1)$  if  $n$  is the maximum positive integer such that there exists an isomorphism from the ball  $B_G(0, n)$  to  $B_H(0, n)$  sending 0 to 0. (Here 0 is any particular point of  $G$  or  $H$ , and  $B_G(0, n)$  denotes the set of all points at graph distance at most  $n$  from 0.) This is a natural metric to use on  $Q$ ; see for example [1]. The following easy compactness argument shows that it is indeed a metric.

**Proposition 1.** *Let  $G, H \in Q$  with  $d(G, H) = 0$ . Then  $G$  and  $H$  are isomorphic.*

**Proof.** For each  $n$ , we have an isomorphism  $\theta_n : B_G(0, n) \rightarrow B_H(0, n)$  sending 0 to 0. Now, there are only finitely many choices for an isomorphism from  $B_G(0, 1)$  to  $B_H(0, 1)$ , so among the restrictions  $\theta_1|_{B_G(0, 1)}, \theta_2|_{B_G(0, 1)}, \dots$  there are infinitely many that agree: say

$$\theta_{i_1}|_{B_G(0, 1)} = \theta_{i_2}|_{B_G(0, 1)} = \dots = \bar{\theta}_1.$$

Then, among the restrictions  $\theta_{i_1}|_{B_G(0, 2)}, \theta_{i_2}|_{B_G(0, 2)}, \dots$  there must be in-

finitely many that agree: say

$$\theta_{j_1}|_{B_G(0,2)} = \theta_{j_2}|_{B_G(0,2)} = \dots = \bar{\theta}_2.$$

Continuing in this way, we obtain a sequence of isomorphisms  $\bar{\theta}_n : B_G(0,n) \rightarrow B_H(0,n)$  with the property that for all  $m \leq n$  we have  $\bar{\theta}_n|_{B_G(0,m)} = \bar{\theta}_m$ . It follows that the union  $\bigcup_{n \geq 1} \bar{\theta}_n$  is a (well-defined) isomorphism from  $G$  to  $H$ .  $\square$

A very similar argument shows that  $Q$  is compact:

**Proposition 2.** *Every sequence in  $Q$  has a convergent subsequence.*

**Proof** (sketch). Let  $G_1, G_2, \dots$  be any sequence of graphs in  $Q$ , each with a chosen point 0. Infinitely many of the  $G_i$  must have isomorphic 1-balls  $B_{G_i}(0,1)$ : say  $B_{G_{i_1}}(0,1), B_{G_{i_2}}(0,1), \dots$  are all isomorphic (with 0 mapping to 0). Among  $G_{i_1}, G_{i_2}, \dots$  we can find infinitely many graphs whose 2-balls are isomorphic (extending the isomorphisms of their 1-balls), and so on.

Continuing in this way, and choosing suitable partially nested isomorphisms to some fixed reference set  $X$  of vertices, we build up a nested sequence of finite graphs whose union  $G$  is a graph on  $X$ . Then  $G$  is connected and  $r$ -regular. To show that  $G$  is transitive, it is enough to show that for every choice of  $x, y \in X$  and every  $n$  there is an isomorphism  $B_G(x,n) \rightarrow B_G(y,n)$  mapping  $x$  to  $y$ ; then the method of the proof of Proposition 1 yields an automorphism of  $G$  that takes  $x$  to  $y$ . But this is immediate:  $B_G(x,n)$  and  $B_G(y,n)$  are both contained in some ball  $B_G(0,m)$ ; this ball coincides with the ball  $B_{G_i}(0,m)$  in each of the graphs  $G_i$  of our  $m$ th subsequence; and  $G_i$  (being transitive) has an automorphism that takes  $x$  to  $y$ , and therefore also  $B_G(x,n)$  to  $B_G(y,n)$ . Thus,  $G \in Q$ .

Finally, it is clear that any diagonal subsequence of the subsequences of  $G_1, G_2, \dots$  that we have chosen converges to  $G$ , as required.  $\square$

We remark in passing that, although it does not seem to help us, it is interesting to note that the set of Cayley graphs is a closed subset of  $Q$ : this may be proved by arguments similar to those in the proof of Proposition 2.

Let  $G$  be any limit point of the sequence  $G_1, G_2, \dots$  (A little thought shows that this sequence is actually convergent and thus has a unique limit; we shall prove this formally in the next section.) Is  $G$  still quasi-isometric to  $T_5$ ? No, it is not: it will not be difficult to prove (see the next section) that  $G$  has only one end, and so cannot be quasi-isometric to  $T_5$ .

Of course, it is very hard to think about an abstract limit graph. Luckily, there is a far more down-to-earth description of  $G$ , which we give now.

### 3. An explicit construction

Our starting point here is that the (directed) line graph  $D_1$  of  $D_0$  is precisely the set of all directed paths in  $D_0$  of length 1, with path  $uv$  joined to path  $wx$  if  $v = w$ . Similarly  $D_2$ , the line graph of the line graph of  $D_0$ , can be thought of as the set of all directed paths in  $D_0$  of length 2, with  $uvw$  joined to  $xyz$  if  $v = x$  and  $w = y$ . And so on:

**Proposition 3.** *The directed graph  $D_n$  is isomorphic to the graph whose vertices are the directed paths of length  $n$  in  $D_0$ , with an arc from  $x_1x_2 \dots x_{n+1}$  to  $y_1y_2 \dots y_{n+1}$  if  $y_i = x_{i+1}$  for all  $1 \leq i \leq n$ .*

**Proof.** Induction on  $n$ . □

Let us see what, when  $n$  is large, a ‘small’ neighbourhood (of radius much less than  $n$ ) of a vertex  $v \in G_n$  looks like. Let  $P$  be the path in  $D_0$  corresponding to  $v$ . Suppose that we wish to move from  $v$  to one of its five neighbours  $v'$  in  $G_n$ : how do we obtain the path  $P'$  corresponding to  $v'$  from the path  $P$ ? If the edge  $e = vv'$  is directed from  $v$  to  $v'$  in  $D_n$ , then  $P'$  is obtained from  $P$  by moving the last vertex of  $P$  to one of its three out-neighbours in  $D_0$ , while all the other vertices of  $P$  simply move to their successors along  $P$ . Similarly, if  $e$  is directed from  $v'$  to  $v$ , we obtain  $P'$  from  $P$  by moving the first vertex of  $P$  to one of its two in-neighbours in  $D_0$ , while all the other vertices of  $P$  are forced: they just move to their predecessors on  $P$ . See Figure 3.

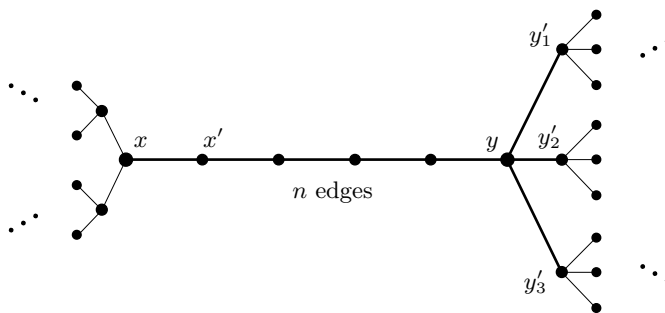


FIGURE 3. A path  $x \dots y \subset D$  corresponding to a vertex  $v \in D_n$ , and the paths  $x' \dots y_i \subset D$  corresponding to the 3 out-neighbours of  $v$  in  $D_n$

So what does the open  $n/2$ -neighbourhood  $N$  of a point  $v \in G_n$  look like? If (the path of)  $v$  has start vertex  $x$  and end vertex  $y$ , then the set of the start vertices of the points of  $N$  is disjoint from the set of their end vertices: indeed, these sets are contained in the open balls of radius  $n/2$  about  $x$  and  $y$  respectively. So we may view the start and end vertices as behaving ‘independently’: as long as we stay in the ball of radius  $n/2$  about  $v$ , the start vertices trace out

part of a tree of in-degree 2 and out-degree 1, while the end vertices trace out part of a tree of in-degree 1 and out-degree 3.

This motivates the following explicit definition of a graph  $G^*$ , which will turn out to be the unique limit of our sequence  $G_1, G_2, \dots$ . Let  $E$  be a 3-regular tree, oriented to have in-degree 2 and out-degree 1, and let  $F$  be the oriented 4-regular tree of in-degree 1 and out-degree 3. Fix a point  $0 \in E$  and a point  $0 \in F$ . Let the *rank*  $r(x)$  of a point  $x \in E$  be the signed distance from 0 to  $x$  (so if the unique undirected path from 0 to  $x$  in  $E$  has  $s$  forward edges and  $t$  backward edges then  $r(x) = s - t$ ), and define  $r(y)$  in the same way for  $y \in F$ . Now define the directed graph  $D^*$  as follows. The vertex set of  $D^*$  is the set  $\{(x, y) \in E \times F : r(x) = r(y)\}$ , and  $D^*$  has an arc from  $(x, y)$  to  $(x', y')$  whenever  $xx' \in E$  and  $yy' \in F$  (Figure 4). Finally, let  $G^*$  be the undirected version of  $D^*$ .

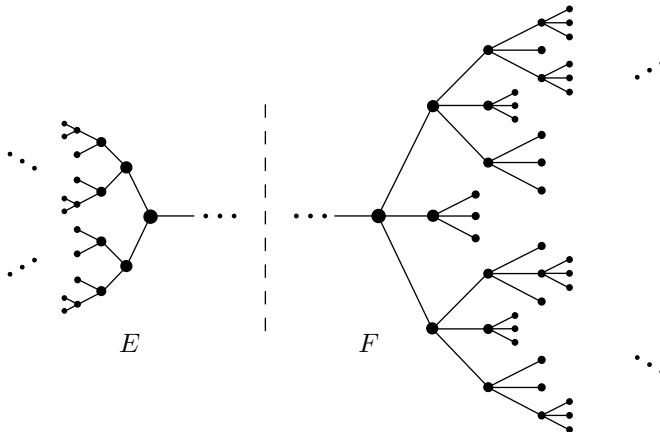


FIGURE 4. All directions are from left to right

Let us verify that  $G^*$  is indeed the unique limit of the sequence  $G_1, G_2, \dots$ :

**Proposition 4.** *The sequence  $(G_n)$  converges to  $G^*$ .*

**Proof.** The directed graphs  $D_n$  and  $D^*$  have isomorphic  $n/2$ -neighbourhoods, so  $d(G_n, G^*) \leq \frac{2}{n+2}$ .  $\square$

We remark that it is now possible to define precisely what we mean by ‘large  $K_{2,3}$ s’ in the graph  $G^*$ . Given a vertex  $(x, y)$  of  $G^*$ , we have  $r(x) = r(y)$  by definition of  $G^*$  and call this number the *rank* of  $(x, y)$ , denoted again by  $r(x, y)$ . Given an integer  $k > 0$ , we call each of the (isomorphic) components of the subgraph of  $G^*$  spanned by the vertices of rank between 0 and  $k$  a  $K_{2,3}$  of order  $k$ . It is not difficult (if a little tedious) to write down a formal partition of the vertex set of such a  $K_{2,3}$  of order  $k$  into five classes, together with an adjacency rule between these classes based on adjacencies in  $G^*$ , so that the

resulting graph is indeed a  $K_{2,3}$ . Instead, we offer a picture of a  $K_{2,3}$  of order 4, shown in Figure 5.

Perhaps the most tangible evidence that we have for our conjecture that  $G^*$  is not quasi-isometric to a Cayley graph is that it is certainly not quasi-isometric to the obvious candidate of such a Cayley graph, the graph  $T_5$ :

**Proposition 5.**  $G^*$  has only one end.

**Proof.** We show that the deletion of any finite set  $S$  of vertices from  $G^*$  leaves only one infinite component. Let  $r$  be the smallest and  $s$  the largest rank of a vertex in  $S$ , and let  $S'$  be the set of all vertices that can be reached from  $S$  by a path whose vertices all have rank between  $r$  and  $s$ . Clearly  $S'$  is finite, so it suffices to show that  $G^* - S'$  is connected.

Let vertices  $(x_1, y_1), (x_2, y_2) \in G^* - S'$  be given, and let us show that we can move a token vertex  $(x, y)$  from  $(x_1, y_1)$  to  $(x_2, y_2)$  in  $G^*$  without hitting  $S'$ . We may assume that  $s < r(x_1, y_1) \leq r(x_2, y_2)$ : the proof for  $r(x_1, y_1) \leq r(x_2, y_2) < r$  is analogous, and any vertex of rank between  $r$  and  $s$  can be joined to a vertex of rank  $> s$  by any path of increasing rank (which avoids  $S'$  by definition of  $S'$ ).

Starting with  $(x, y) = (x_1, y_1)$ , we first move  $(x, y)$  towards the right in Figure 4 (formally: with increasing rank, and thus avoiding  $S'$ ) until  $x$  lies on a left (i.e. backward oriented) ray  $R$  in  $E$  that avoids  $S'_E$ , the set of first components of the vertices in  $S'$ . We now move  $(x, y)$  to the left, keeping  $x$  on  $R$ , until  $y$  lies to the left of  $y_2$  in  $F$ . We then move  $(x, y)$  right again until  $y = y_2$ ; since  $x$  stays on  $R$  during this move, this keeps us outside  $S'$  until we are back at points of rank  $> s$ . We now move on towards the right until  $x$  lies to the right of  $x_2$  in  $E$ , and back again until  $(x, y) = (x_2, y_2)$ .  $\square$

How might one show that  $G^*$  is not quasi-isometric to a Cayley graph? The first hope, of course, would be to imitate our proof of why  $H$  is not a Cayley graph, using a sufficiently large  $K_{2,3}$  instead of the actual  $K_{2,3}$ s in  $H$ . However, we have been unable to make this approach work and are not sure that it can work: although it is straightforward to translate the canonical group action on a hypothetical Cayley graph quasi-isometric to  $G^*$  to similar ‘quasi-automorphisms’ of  $G^*$ , the fuzziness introduced seems to blur the difference between the sizes of the two vertex classes even of large  $K_{2,3}$ s (which are  $2^n$  and  $3^n$ , respectively), a difference central to the ‘non-Cayley’ proof for  $H$ .

As a more global approach we might try to show that every quasi-automorphism of  $G^*$  preserves the natural orientation of all sufficiently large  $K_{2,3}$ s, mapping their left sets (their vertices of minimal rank) to the left of the images of their right sets (their vertices of maximal rank). Then any Cayley graph quasi-isometric to  $G^*$  would have two ‘directions’ invariant under all its automorphisms (not just under its own group action), and in which it grows at different speeds:  $2^n$  ‘to the left’ and  $3^n$  ‘to the right’. Can this happen in a



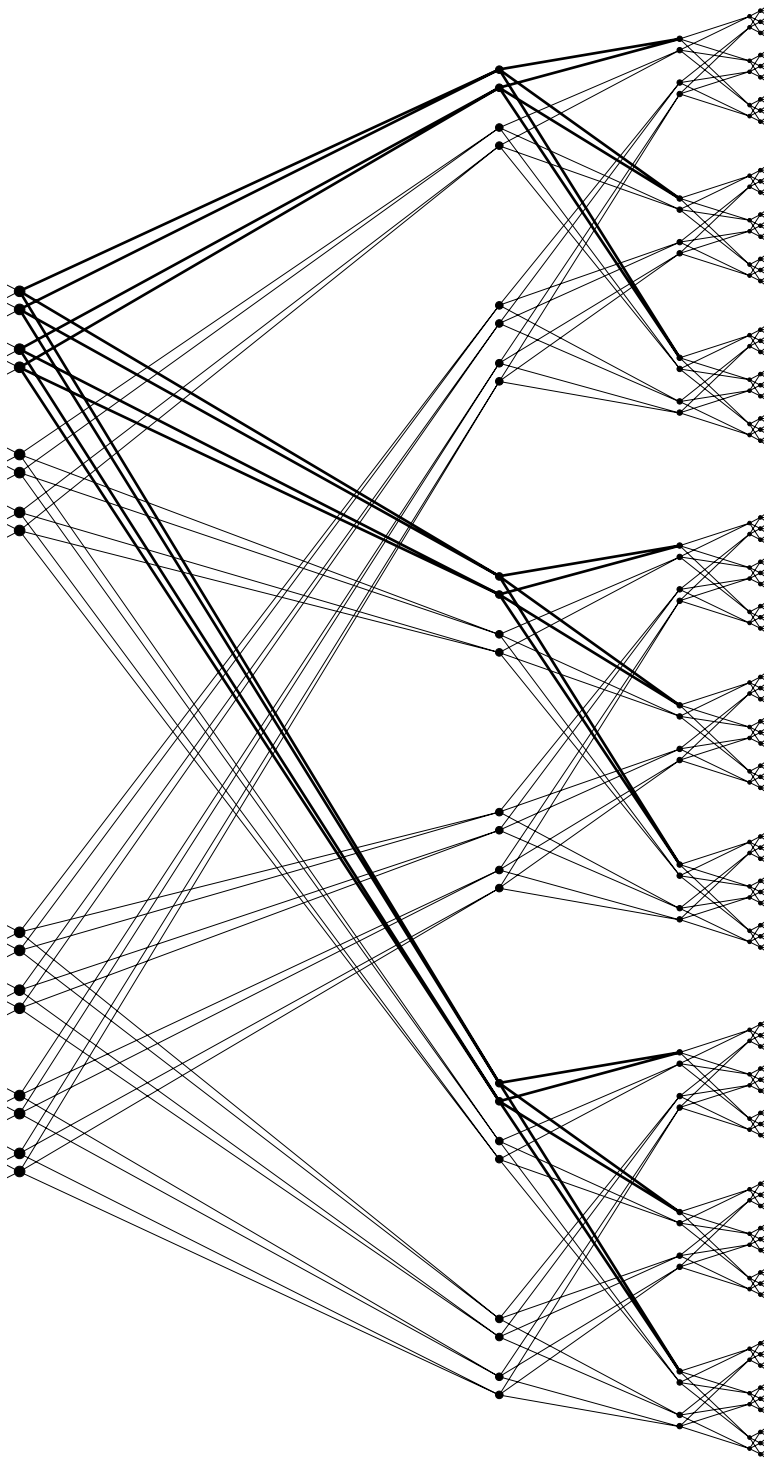


FIGURE 5. A  $K_{2,3}$  of order 4 in  $G^*$ , and a (bold)  $K_{2,3}$  of order 2

Cayley graph? (Recall that the overall growth speed of a graph is not preserved under quasi-isometries: for example, the trees  $T_3$  and  $T_4$  are quasi-isometric.)

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